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# INTRODUCTION

## Document overview

This document presents the software requirements specifications of 101 software development project.

It describes:

* Requirements of functionalities, performances, interfaces, environment …
* Tests principles and definitions of validation methods of requirements,
* The compliance of requirements to customer needs,
* The relative importance and precedence of requirements

## Abbreviations and Glossary

### Abbreviations

Add here abbreviations

### Glossary

Add here words definitions

## References

### Project References

| # | Document Identifier | Document Title |
| --- | --- | --- |
| [R1] | ID | Integrative Project |

### Standard and regulatory References

|  |  |  |
| --- | --- | --- |
| # | Document Identifier | Document Title |
| [STD1] | Tema: 1.2.1. "SPICE", "CMMI" | [ISO/IEC 15504, CMMI](https://ingertec.com/cmmi-o-iso-iec-15504/)  [ISO/IEC 9899-2011](stakeholder/ISO_IEC9899.pdf)  ISO/IEC 19769:2004  ISO/IEC 9899:tc2 |

## Conventions

Requirements listed in this document are constructed according to the following structure:

|  |  |
| --- | --- |
| Requirement ID | SRS-101-000 |
| Title | Title of XXX-000 requirement |
| Description | Description of XXX-000 requirement |
| Version | Version of XXX-000 requirement |

|  |  |
| --- | --- |
| Requirement ID | SRS-Power input -001 |
| Title | Main power input |
| Description | The power voltage supply must be 12 Volts DC. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Work load frequency range-002 |
| Title | Main work load frequency range |
| Description | The frequency work load shall be in the f = 100 Hz to f = 1 KHz, range. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM Duty Cycle-003 |
| Title | Main duty cycle |
| Description | The PWM duty cycle shall be defined after working frequency. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Set point (Speed)-004 |
| Title | Main set- point range |
| Description | The set point shall be defined within the range 0 to 3000 RPM |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Display behaviour-005 |
| Title | Main information displayed |
| Description | The LCD shall display the motor speed, set point and square signal work percentage. |
| Version | V1.0 |

# REQUIREMENTS

## States

FOO software works in three states:

* Starting: the software loads its components;
* In use: all the functionalities of the software are available to the users;
* Stopping: the software is being stopped.
* Maintenance: the software is in maintenance mode

States and transitions. (Need diagram--UML)

## Functionalities and Performance

This is the core of the SRS. It contains the purpose of the software expressed in technical requirements.

|  |  |
| --- | --- |
| Requirement ID | SRS-VOLTAGE |
| Title | Voltage |
| Description | FOO hardware shall deliver 12V |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-SetPoint |
| Title | SetPoin |
| Description | HARDWARE\_CONFIGURATION for the SetPoint shall be defined as designed and specified in the Integrative Project document, page 6. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-SetPoint\_Adjustment |
| Title | Setpoint\_Adjustment |
| Description | HARDWARE\_CONFIGURATION for SetPoint shall set reference values using the potentiometer as defined in the Integrative Project document, page 6 – fig 5. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS- SetPoint\_Noise\_Atenuation |
| Title | Setpoint SetPoint\_Noise\_Atenuation |
| Description | HARDWARE\_CONFIGURATION SetPoint offset value shall be defined by sampling the signal at 100ms period.  Sampling shall be average to yield offset value. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS- SetPoint\_Reference\_Value\_UART |
| Title | SetPoint\_Reference\_Value\_UART |
| Description | HARDWARE\_CONFIGURATION SetPoint offset values must be tested as defined in the Integrative Project design document, page 6 using the UART protocol.  Offset\_ updated \_messsage shall be set to 200 ms.  UART\_transmition\_velosity shall be set to 115200 bps |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM |
| Title | HARDWARE\_CONFIGURATION\_PWM |
| Description | HARDWARE\_CONFIGURATION for the PWM shall be defined at a frequency of 1Khz of duty cycle. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM |
| Title | HARDWARE\_CONFIGURATION\_PWM |
| Description | HARDWARE\_CONFIGURATION for the PWM shall be sampled with in a period of 100ms. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM |
| Title | HARDWARE\_CONFIGURATION\_PWM |
| Description | HARDWARE\_CONFIGURATION for the interface shall set discreate values of RPM corresponding to percentage of signal duty cycle as defined in value table in the Integrative Project document, page 6 – table 1. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM |
| Title | HARDWARE\_CONFIGURATION\_PWM |
| Description | HARDWARE\_CONFIGURATION for the tachometer shall set discreate values of RPM corresponding to percentage of signal duty cycle as defined in value table in the Integrative Project document, page 6 – table 1. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-PWM |
| Title | HARDWARE\_CONFIGURATION\_PWM |
| Description | HARDWARE\_CONFIGURATION shall set the output of the Hall\_effect sensor to a square signal. |
| Version | V1.0 |

## SW\_Configuration

|  |  |
| --- | --- |
| Requirement ID | SRS-Model |
| Title | Speed control |
| Description | Speed control shall compute the PWM control signal with the 100 ms parameter, with the use of the PID algorithm. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Model |
| Title | Speed control |
| Description | Speed control shall set the motor to the RPM, using the ACD feedback and varying voltage from SetPoint |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Controller |
| Title | Speed control\_setpoint |
| Description | Setpoint value shall be read every 100ms. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-Controller |
| Title | Speed\_transfer function |
| Description | The [transfer function](#_Verification__Transfer_function) shall be used to generate a speed control |
| Version | V1.0 |

## Human\_Machine\_Interface

|  |  |
| --- | --- |
| Requirement ID | SRS- HMI\_Display |
| Title | HMI\_Display |
| Description | HMI\_Display software shall display the following items:  **Name of the project:** Speed Control DC motor  **Duty cycle:** XXX %  **Speed:** XXXX RPM  **SW:** X.X  **HW:** CESEQ-C001 / CESEQ-P001  **Developer:** Lastname1, Name1  Lastname2, Name2 |
| Version | V1.0 |

## Regulatory requirements

|  |  |
| --- | --- |
| Requirement ID | SRS-Speed control |
| Title | About SP\_C |
| Description | SP\_C display shall display an “About…” Tag. This window displays the current version of the application. |
| Version | V1.0 |

## System Integration

Software shall be integrated in the following six steps:

1. Gather requirements as done in this document.
2. Analysis.
3. Architecture design.
4. Systems integration design.
5. Implementation.
6. Maintenance.

## External interfaces

This section describes hardware and software interfaces of the software in the system

### Hardware interfaces

add requirements about integration of software and hardware.

### Hardware resources

|  |  |
| --- | --- |
| Requirement ID | SRS-Speed\_Control (SP\_D)- Renesas |
| Title | Hardware configuration |
| Description | SP\_Cshall run with the expected response times on a Synergy S7G2 MCU with the following minimal configuration:   * 2 Go RAM * ... |
| Version | V1.0 [stakeholder\r12um0004eu0100\_synergy\_sk\_s7g2.pdf](stakeholder/r12um0004eu0100_synergy_sk_s7g2.pdf) |

### Software resources

|  |  |
| --- | --- |
| Requirement ID | SRS-SP\_C-SW |
| Title | Software configuration\_ SP\_C-SW |
| Description | SP\_C-SW runs in the following software environment:   * Renesas e2 estudio \_ V6.2.0 |
| Version | V1.0 [stakeholder\Installation Instructions.pdf](stakeholder/Installation%20Instructions.pdf) |

## Verification\_ Transfer function

* Special transfer function shall be modeled and defined using Matlab (Program to generate transfer function is optional).
* The transfer function shall be implemented in the code to control the speed of the motor.

|  |  |
| --- | --- |
| Requirement ID | SRS-MATLAB\_ Transfer function (TF) |
| Title | MATLAB\_R2017b |
| Description | TF shall be delivered on a file generated by MATLAB “TF.m” |
| Version | V1.0 |

## Packaging and installation

|  |  |
| --- | --- |
| Requirement ID | SRS-XXX-PAK-010 SAMPLE |
| Title | Packaging |
| Description | XXX shall be delivered on zzz media. |
| Version | V1.0 |

|  |  |
| --- | --- |
| Requirement ID | SRS-XXX-PAK-010 SAMPLE |
| Title | Install-shield |
| Description | XXX shall be installed with the use of an install shield. |
| Version | V1.0 |

# VERIFICATION METHODS

The verification methods of the requirements are defined below:

* Inspection (I): control or visual verification
  + Control of the physical implementation or the installation of a component. The control verifies that the implementation or the installation of a component is compliant with the requirements of diagrams.
  + Control of the documentation describing a component. The control verifies that the documentation is compliant with the requirements.
* Analysis (A): verification based upon analytical evidences
  + Verification of a functionality, performance or technical solution of a component by analyzing the data collected by tests in real conditions, by simulation of real conditions or by a analysis report.
  + Analysis of test data or of design data is used as appropriate to verify requirements.
  + The verification is based upon analytical evidences obtained by calculations, like modeling, simulation and forecasting.
  + Analysis is used when an acceptable level of confidence cannot be established by other methods or if analysis is the most cost-effective solution.
* Demonstration (D): verification of operational characteristics, without quantitative measurement
  + Verifying a requirement by demonstration implies that the required functionality specified by a requirement is complete.
  + Demonstration is used when quantitative measurement is not required for verification of the requirements
  + Demonstration includes the control of the technical solutions specified by the non-functional requirements.
* Test (T): verification of quantitative characteristics with quantitative measurement
  + Verifying a functionality, performance or technical solution of a component by executing testing scenarios in predefined, controlled and traceable testing conditions.
  + Tests require the use of special equipment, instrumentation, simulation techniques, or the application of established principles and procedures,
  + Data produced during tests is used to evaluate quantitative results and compare them with requirements.

For each requirement of the SRS, a verification method is defined. Method is abbreviated I, A, D or T.

|  |  |  |
| --- | --- | --- |
| Requirement ID | Requirement Title | Method |
| REQ-001 | Verify that the speed is displayed in rpm | D |
| REQ-001 | Verify that the color of background is blue | I |

Note: do not mistake the two meanings of the word “test” in this document:

* The method of verification, named Test and abbreviated (T), as defined above.
* A test, or test case, is a sequence of actions to verify a requirement. Tests are defined in the software test plan.

Examples of tests methods:

Inspection:

* Verify that the color of background is blue,
* Verify that the user manual has the CE mark on its cover
* Verify that the PC has 4Gb memory
* Verify that firmware version on electronic card is 1.0.1

Demonstration

* Verify that when the user closes the window, a confirmation message appears
* Verify that the file is saved in the output directory
* Verify that the result is shown
* Verify that if a value is out of range, a warning is displayed

Analysis:

* Verify that the statistical distribution of results of xxx algorithm is a Gaussian with mean=x and stdev=y, when input data are blah blah
* Verify that the linear regression of results of xxx algorithm is a line which value is 1 on the y-axis, at zero on the x-axis,

Test:

* Verify that a file of 1Gb is processed in less than 3s
* Verify that the response time of the server is 15ms with 20 simultaneous requests

Rule of thumb for software, 80% of requirements are verified by demonstration, 15% by inspection and 5% by analysis or test methods.

# REQUIREMENTS TRACEABILITY

Add a table with traceability of software requirements of this document with user or system requirements.

Example

|  |  |  |  |
| --- | --- | --- | --- |
| SRS Req. | Req Title | Functional Req. | Req. Title |
| SRS-REQ-001 | Reading ECG values | FUN-REQ-00A | ECG post treatment |
| SRS-REQ-002 | Writing results | FUN-REQ-00A | ECG post treatment |

# CRITICAL REQUIREMENTS

If necessary, add a list of critical requirements, or a list of reference to requirements in previous sections.

This list may be the result of risk analysis (ISO 14971).

Examples

|  |  |  |
| --- | --- | --- |
| Requirement ID | Requirement Title | Origin |
| REQ-001 | Alarm when value out of range | Risk Analysis |
| REQ-002 | Do not open file if no patient name | Risk Analysis |
| REQ-003 | Display negative values in red color | Human factor engineering |